

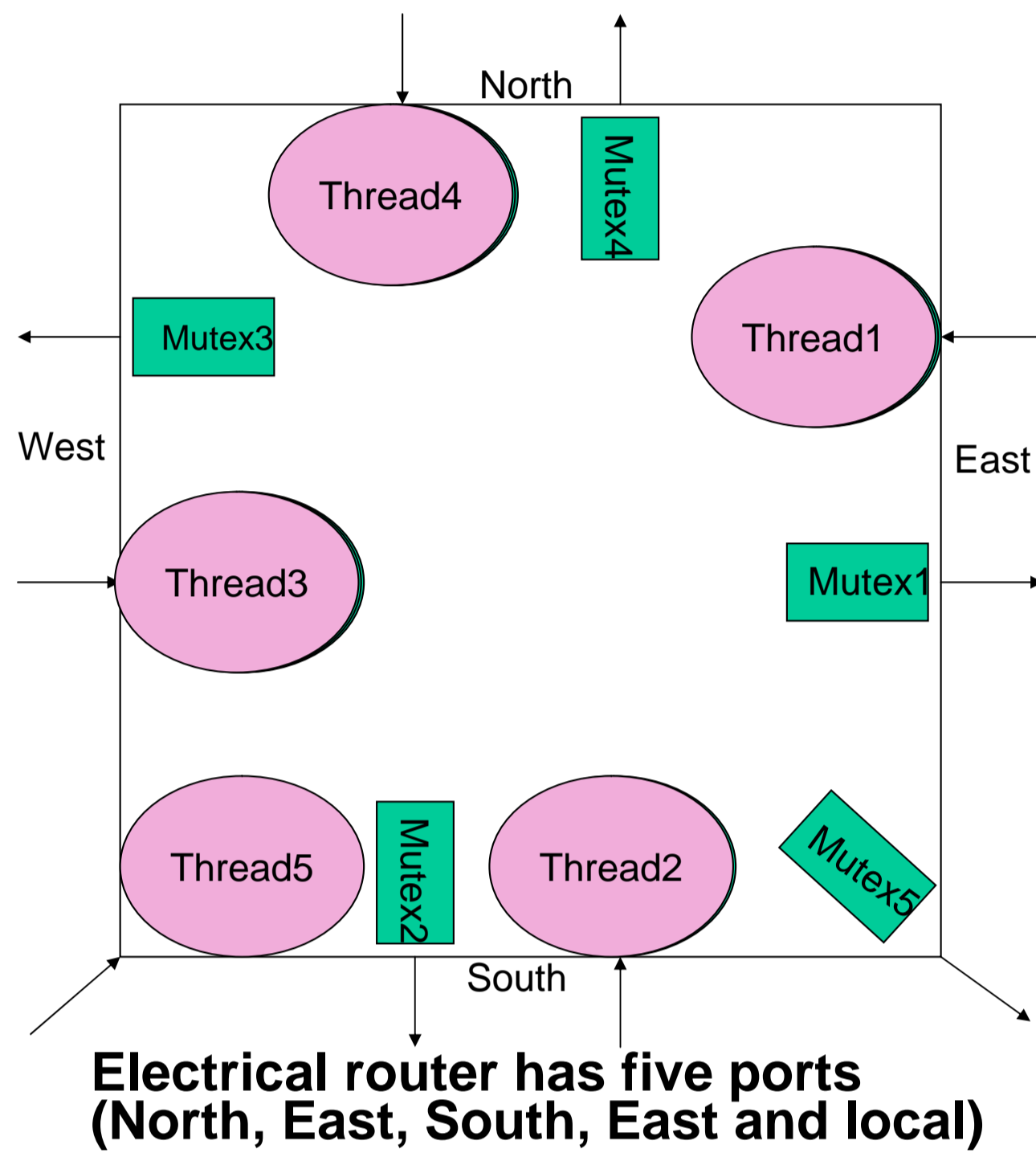
### I. Introduction

With the increasing complexity of multiprocessor systems-on-chip (MPSoC), global communication on chip has become a major challenge for system performance improvement within restricted power and area budgets. Network-on-chip (NoC) is emerging as an alternative to existing dedicated interconnection and shared bus. This poster will firstly present our studies based on electrical and optical routing model. Considering the difficulty of run-time management of the communication among the multiprocessors, especially flow control from the local resources in NoC, which may contain hundreds and thousands of IPs, we use the controllable and observable method by constructing a state space model to overcome this problem. Then we propose some routing topologies with the three dimension, which mix CMOS layer & optical layer. The heterogeneous system is discussed at last.

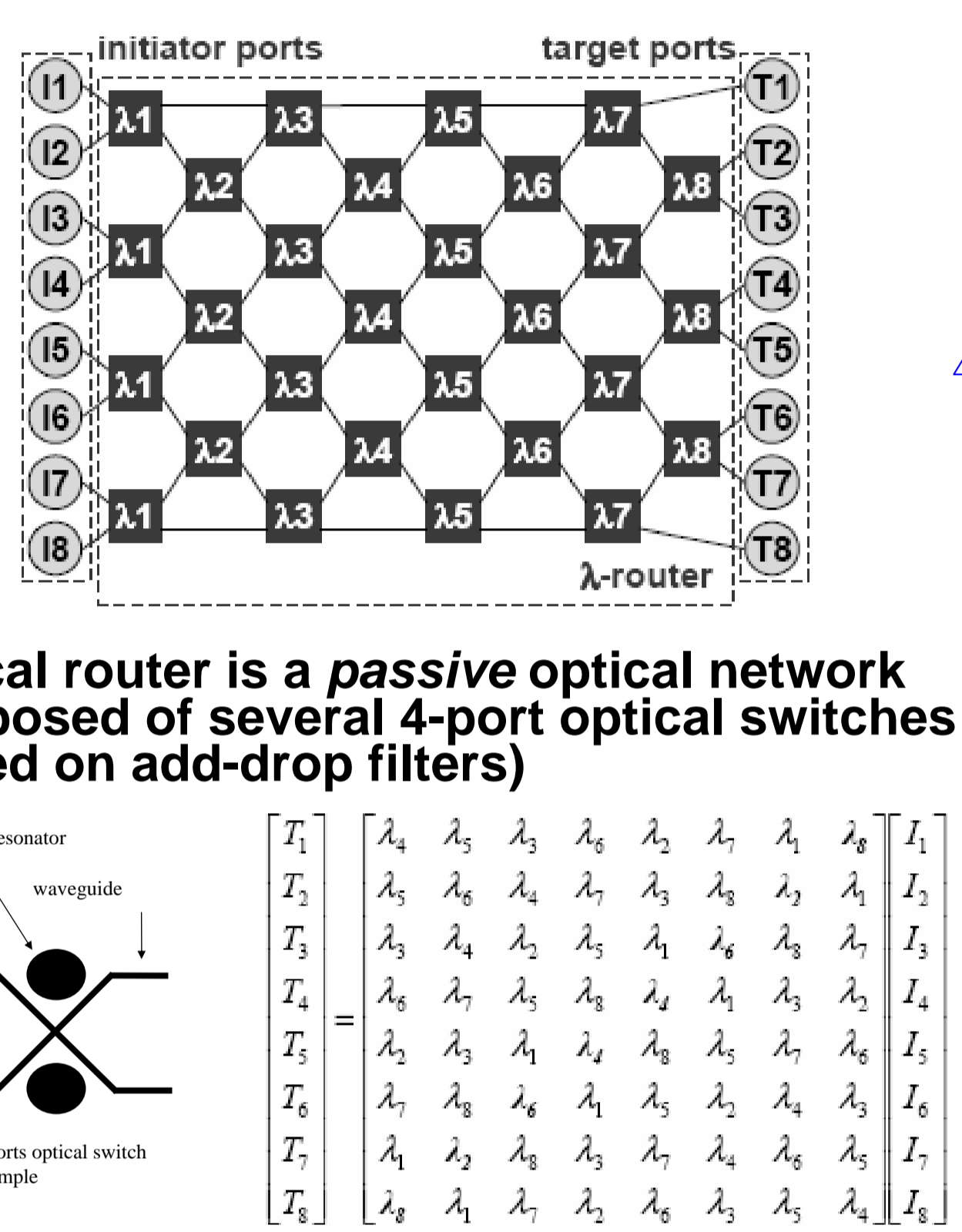
### II. Routing model

To study the performance of the network on chip, we construct the nodes of the network: the router. Two types of routing model, electrical routing model and optical routing model have been considered.

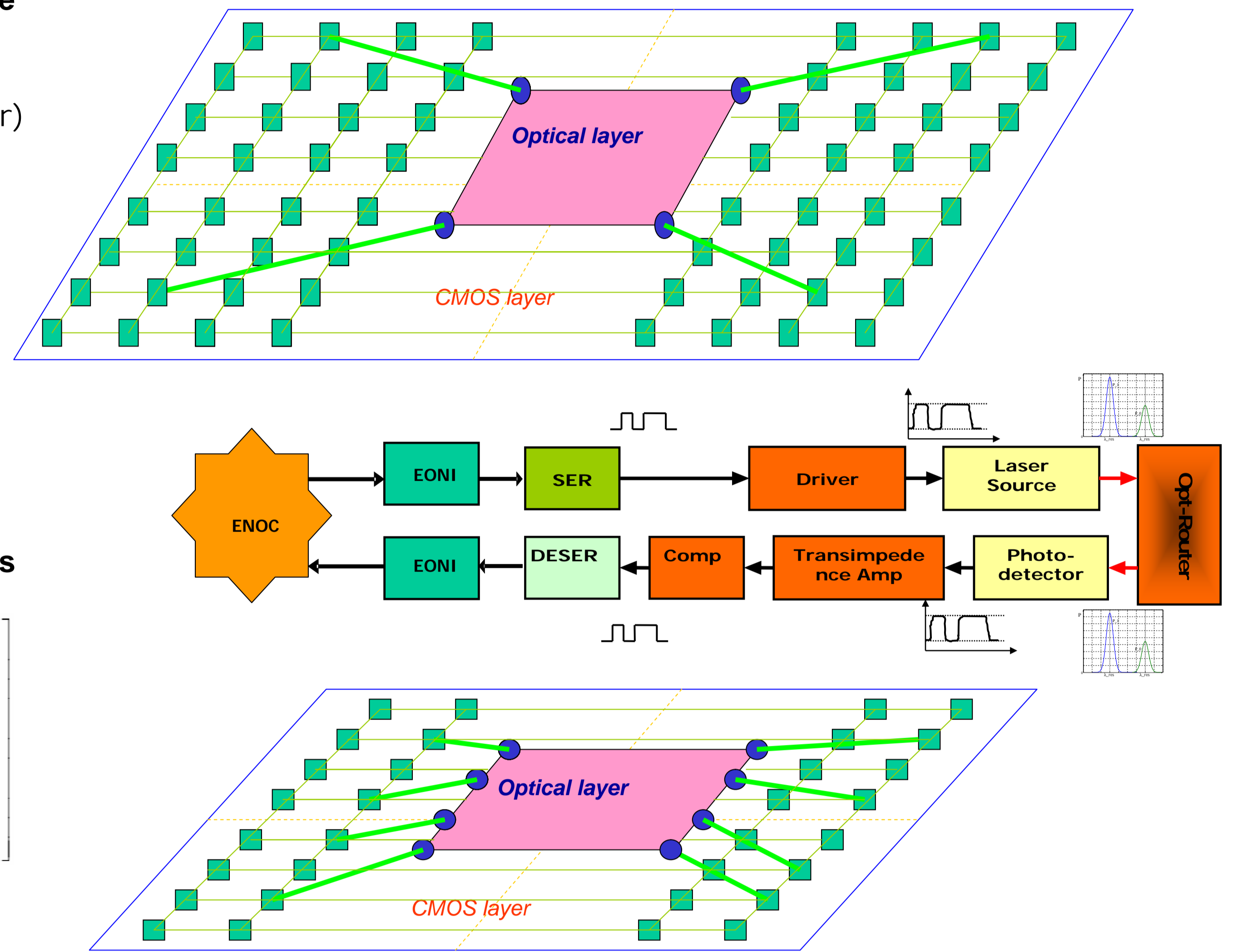
#### A. Electrical routing model



#### B. Optical routing model ( $\lambda$ router)

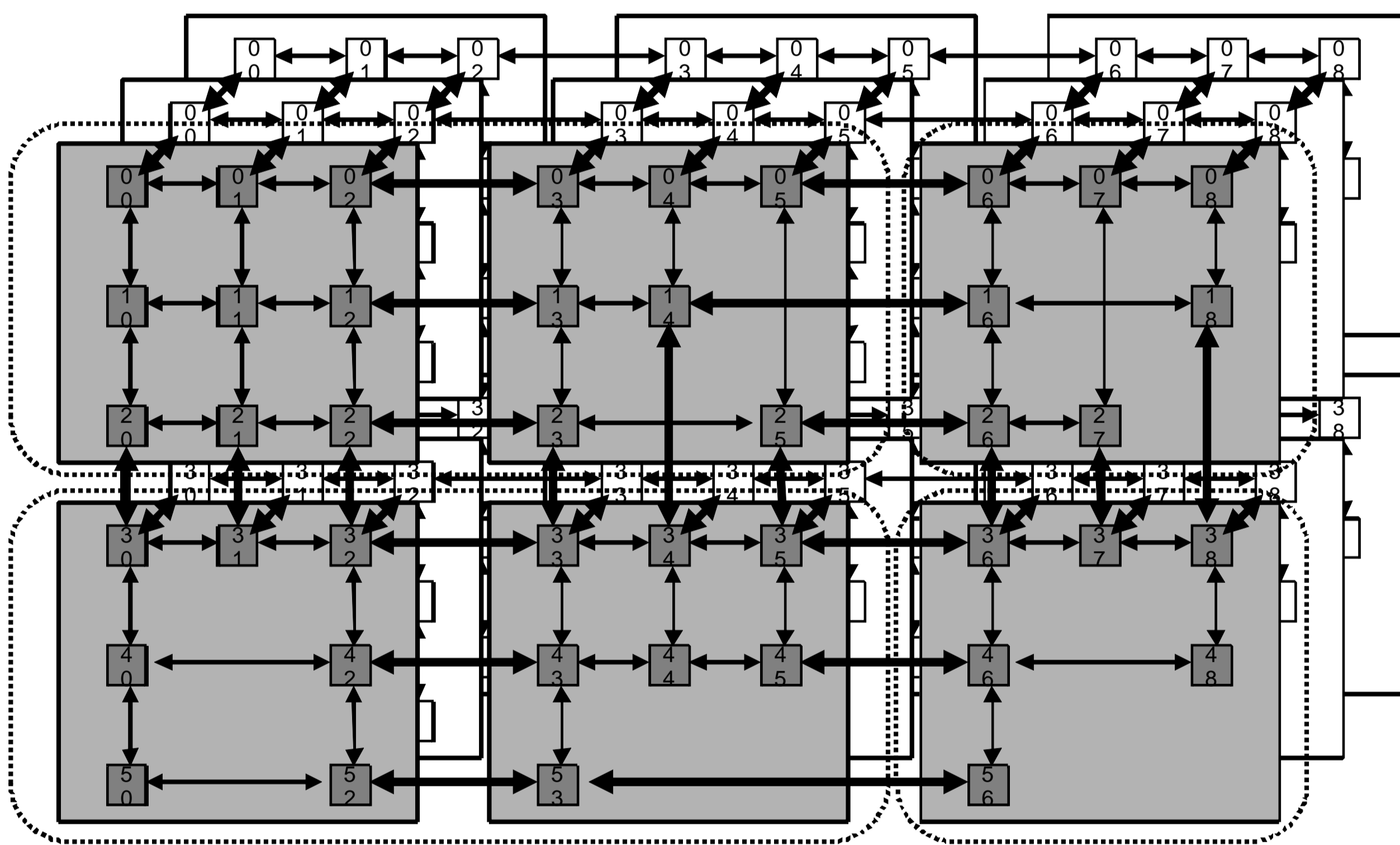


### IV. Integrating electrical and optical routing design



### III. 3D topology of NoC

A clustered hierarchical NoC topology is composed of several irregular meshes.



#### Routing algorithm of the irregular 3D ENoC:

The wormhole routing algorithm used here is hardwired and deterministic;

The first row and the first column are called the main axis;

The routing can be XY or XYX or XYZ or YX or YXY or YXZY according to the places of the source and the destination.

Several restrictions must be followed:

1. There is always a router on the main axis.
2. A router is fully connected if there are other routers in the same axis.

### V. Using state space method to feedback NoC

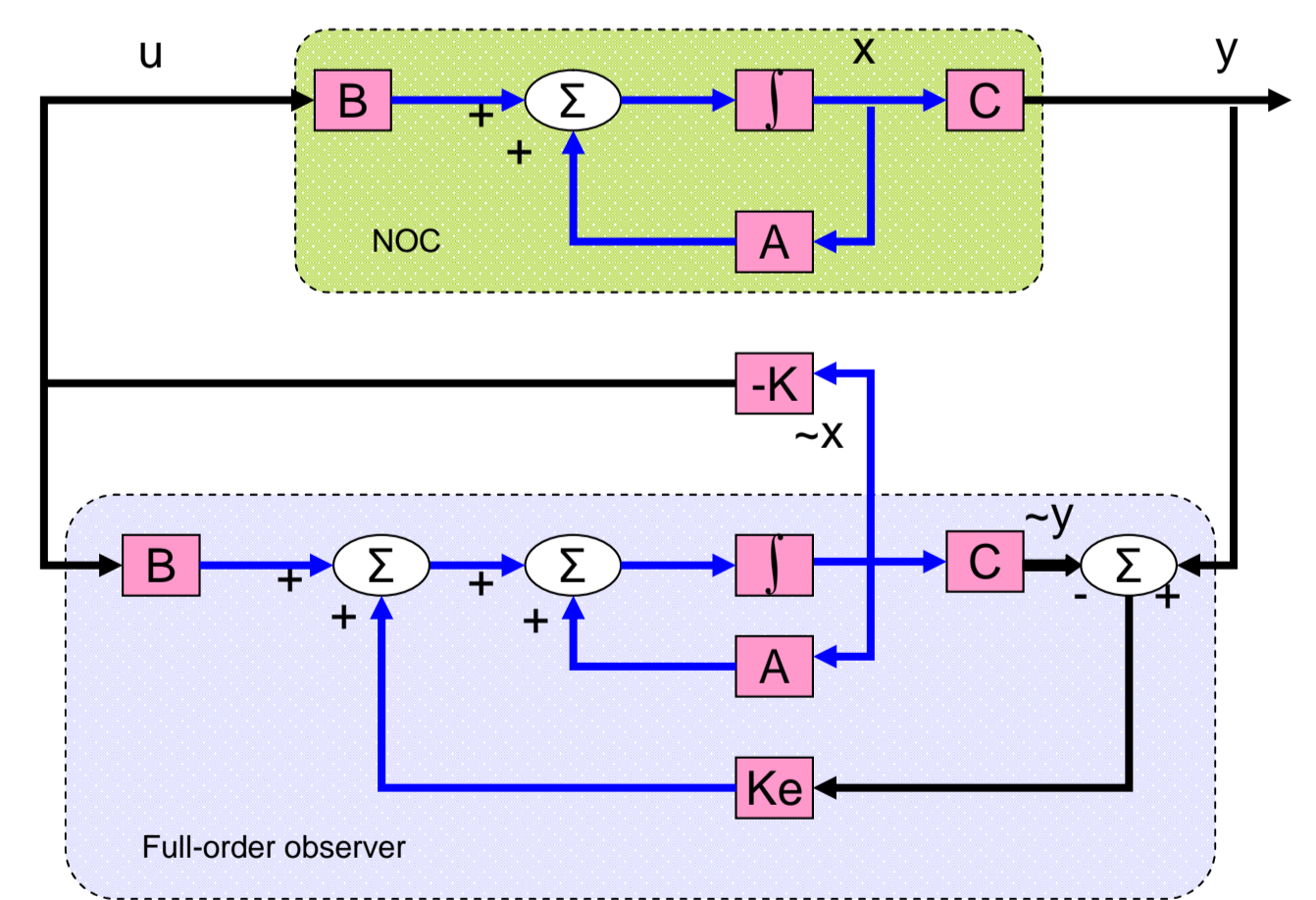
State Equation:  $\frac{dx}{dt} = Ax + Bu$

Output Equation:  $y = Cx + Du$

Full order state observer model:

$$\frac{d\tilde{x}}{dt} = A\tilde{x} + Bu + Ke(y - C\tilde{x})$$

$$= (A - KeC)\tilde{x} + Bu + Ke y$$



- If a NoC contains large number of IPs, controlling the input and output flow rates alone is not sufficient to stabilize the network.
- We try to construct a state space model with state observer controller in its feedback path to monitor the intermediate flow rates and to stabilize the NoC.
- There are two kinds of the observer: full order observer and minimum order observer.

### VI. Discussion of the heterogeneous system

- This poster is dedicated to discuss a heterogeneous system composed of ENoC, ONoC and 3D architecture. In addition, considering the large number IPs NoC, we take the state space method to stabilize the system.
- As the difficulties of 3D, TSV, optical architecture and the implementation of both hardware and software on one chip, the heterogeneous system is still a challenge. The cost performance of the heterogeneous system could be evaluated by our system model.
- Different tools (like SystemC, VHDL, MatLab, MPI) could be used in a heterogeneous system's simulation, but it might result the incompatibility and unavailability of the software that the whole simulation will lost its precise, sometimes will be incorrect. To solve this problem, a simulator of the whole heterogeneous system is under development.

