An Optimized MAC Layer to Physical Device Mapping Methodology Andreea Chis, Eric Fleury, Antoine Fraboulet

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Introduction

• Nodes in WSN severely constrained in resources

- computation
- memory
- energy
- Applications elaborated with energy consumption minimisation as primary goal
- The desired behaviour of embedded systems
 - subject to real-time constraints
 - involves interactions with physical devices with their own individual constraints

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Figure: State machines and automata in systems

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 - optimal reachability in closed systems
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 - optimal control synthesis for automata with acyclic control graphs

• Our goal - provide an optimized mapping of a software protocol on a hardware device

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We address the problem of mapping the *free states* of a software protocol (expressed as a TA) to unique states or paths in the device automaton (behaviour expressed as a TA) such that timing constraints are guaranteed while minimizing the energy consumed

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 - timer events
 - conditioned by logical expressions with clock variables and integer state variables

B-MAC protocol description

Design Goals

B-MAC protocol description

- Design Goals
 - low power operation
 - effective collision avoidance
 - simple implementation
 - efficiency in chanel utilization
 - reconfigurability
 - tolerance to changing network conditions

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scalability

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 - channel arbitration clear channel assessment and packet backoffs
 - reliability link layer acknowledgements
 - low power low power listening

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Radio states classification



- Radio states classification
 - non-transitional duration has a lower bound

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 - non-transitional duration has a lower bound
 - transitional fixed duration

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error

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MAC Automaton Analysis

MAC states

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- MAC states
 - fixed states map directly to physical states of the radio device

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 - on external signals
 - from other layers in the protocol stack
 - not time correlated such an external event can occur at any time while in the free state

MAC Automaton Analysis Physical Automaton Analysis Mapping Decisions

MAC Automaton Analysis

• The signal bottom level - $BL_s(S_{MAC}, S_{PHY})$ - the minimum length of all the elementary paths from S_{MAC} to S_{PHY} in the MAC automaton with first edge a signal enabled transition

MAC Automaton Analysis Physical Automaton Analysis Mapping Decisions

- The signal bottom level $BL_s(S_{MAC}, S_{PHY})$ the minimum length of all the elementary paths from S_{MAC} to S_{PHY} in the MAC automaton with first edge a signal enabled transition
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- Signal enabled transitions are assigned 0 weight
- Timer enabled transitions are assigned weight equal to the state duration
- Bottom Level computation all pairs shortest paths having as intermediate nodes only free states

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Physical Automaton Analysis

• For a path $P = \{s_1, s_2, ..., s_n\}$ in the radio device automaton, a measure of the energy $\mathcal{E}[P]$ consumed :

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$$\mathcal{E}[P] = \sum_{i=1}^{n} P_{s_i} \times t_i.$$

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• The minimum energy consumption

$$\mathcal{E}[P]_{min} = \sum_{i=1}^{n} t_{i_min} \times P_{s_i}$$

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• For a timed path in the radio device automaton of duration t_{path} the extra time w.r.t the minimum transition time of the path t_{min} should be spent in the non-transitional state of the path with the minimum power consumption s_{min}

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$$\mathcal{E}[P_{timed}] = \left\{ egin{array}{cc} \mathcal{E}[P]_{min} + (t_{path} - t_{min}) imes P_{s_{min}} & t_{path} \geq t_{min} \\ \infty & ext{otherwise} \end{array}
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• The distance $dist(S_1, S_2)$ in the physical device automaton the minimum of all the lengths of the elementary paths leading from S_1 to S_2 in the duration-weighted device automaton

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• The set of physical states admissible for S_{MAC}

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 $\begin{aligned} Admissible(S_{MAC}, S_{PHY}) &= \{s \in \textit{Radio_states} | \\ &| \textit{dist}(s, S_{PHY}) \leq \textit{BL}_s(S_{MAC}, S_{PHY}) \}. \end{aligned}$

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$$Admissible(S_{MAC}) = \bigcap_{S_{PHY} \in Sig_Reachable(S_{MAC})} Admissible(S_{MAC}, S_{PHY}).$$

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• The set of physical states admissible as input states for S_{MAC} :

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• The set of physical states admissible as input states for S_{MAC} :

 $\begin{aligned} &Input_Admissible(S_{MAC}, S_{PHY}) = \{s \in \textit{Radio_states} \\ &|\textit{dist}(s, S_{PHY}) - s_{t_{min}} < \textit{BL}(S_{MAC}, S_{PHY})\}, \end{aligned}$

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$$Input_Admissible(S_{MAC}) = \bigcap_{S_{PHY} \in Reach(S_{MAC})} Input_Admissible(S_{MAC}, S_{PHY}).$$

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• The transition into a state *s* from $Input_Admissible(S_{MAC})$ might have to be performed before the beginning of S_{MAC} in order for all the transitions out of S_{MAC} to remain realizable.

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The mapping of S_{MAC}



MAC Automaton Analysis Physical Automaton Analysis Mapping Decisions

The mapping of S_{MAC}

• for a given initial physical state from *Input_Admissible*(S_{MAC}) with remaining time t_{rem}

MAC Automaton Analysis Physical Automaton Analysis Mapping Decisions

The mapping of S_{MAC}

- for a given initial physical state from *Input_Admissible*(S_{MAC}) with remaining time t_{rem}
- the realizable path of minimum energy consumption containing only states from Admissible(S_{MAC})

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The mapping of S_{MAC}

- for a given initial physical state from *Input_Admissible*(S_{MAC}) with remaining time t_{rem}
- the realizable path of minimum energy consumption containing only states from Admissible(S_{MAC})
- ending in a state s from

 ${s \in Input_Admissible(S) | offset(s, S) = 0} \cup$

 $\{s \in \textit{Input}_\textit{Admissible}(S) \land s \in \textit{Admissible}(S_{\textit{MAC}}) | \textit{offset}(s, S) \neq 0\}$

MAC Automaton Analysis Physical Automaton Analysis Mapping Decisions

The mapping of S_{MAC}

- for a given initial physical state from *Input_Admissible*(S_{MAC}) with remaining time t_{rem}
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 - ${s \in Input_Admissible(S) | offset(s, S) = 0} \cup$
 - $\{s \in \textit{Input}_\textit{Admissible}(S) \land s \in \textit{Admissible}(S_{\textit{MAC}}) | \textit{offset}(s, S) \neq 0\}$
- path duration $S_{MAC\,duration} t_{rem} offset(s, S)$.

Energy Consumption Theoretical Analysis Average Energy Consumption

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Performance Evaluation

• Scenario : *n* saturated nodes contend for the channel using B-MAC's CSMA, trying to transmit data to one sink

Energy Consumption Theoretical Analysis Average Energy Consumption

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Performance Evaluation

• Scenario : *n* saturated nodes contend for the channel using B-MAC's CSMA, trying to transmit data to one sink



Energy Consumption Theoretical Analysis Average Energy Consumption

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Energy Consumption Theoretical Analysis Average Energy Consumption

Performance Evaluation

• Scenario : *n* saturated nodes contend for the channel using B-MAC's CSMA, trying to transmit data to one sink



Mappings for backoff states

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Energy Consumption Theoretical Analysis Average Energy Consumption

Performance Evaluation

• Scenario : *n* saturated nodes contend for the channel using B-MAC's CSMA, trying to transmit data to one sink



- Mappings for backoff states
 - map to RX device state

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Energy Consumption Theoretical Analysis Average Energy Consumption

Performance Evaluation

• Scenario : *n* saturated nodes contend for the channel using B-MAC's CSMA, trying to transmit data to one sink



- Mappings for backoff states
 - map to RX device state

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map to IDLE

Energy Consumption Theoretical Analysis Average Energy Consumption

Performance Evaluation

• Scenario : *n* saturated nodes contend for the channel using B-MAC's CSMA, trying to transmit data to one sink



- Mappings for backoff states
 - map to RX device state
 - map to IDLE
 - optimized (IDLE, SLEEP and XOFF) according to the backoff value.

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Energy Consumption Theoretical Analysis

 Analysis - carried out under the assumption of ideal channel conditions (no hidden terminals or capture)

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- Station behavior modelized by a two-stage Markov chain with the goal of determining
 - τ stationary probability that the station transmits in a randomly chosen slot time
 - *p_b* probability of finding the medium busy when performing CCA

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Energy Consumption Theoretical Analysis



Markov chain model for B-MAC backoffs

 $P\{i, k | i, k + 1\} = 1 \qquad k \in (0, W_i - 2), i \in (0, 1)$ $P\{0, k | i, 0\} = \frac{(1 - p_b)}{W_0}, \qquad k \in (0, W_0 - 1), i \in (0, 1)$ $P\{1, k | 0, 0\} = p_b / W_1, \qquad k \in (0, W_1 - 1)$ $P\{1, k | 1, 0\} = p_b / W_1, \qquad k \in (0, W_1 - 1), \text{ for } i \in \mathbb{R}$

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Energy Consumption Theoretical Analysis

• Transmission occurs when the backoff time counter equals 0 and the medium is found not busy while performing clear channel assessment:

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Energy Consumption Theoretical Analysis

• Transmission occurs when the backoff time counter equals 0 and the medium is found not busy while performing clear channel assessment:

$$au = (1 - p_b) imes \sum_{i=0}^{1} b_{i,0} = rac{1 - p_b}{(1 - p_b) imes rac{W_0 + 1}{2} + p_b imes rac{W_1 + 1}{2}}$$

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 Non-linear system of equations in the two unknowns τ and p_b that can be solved using numerical techniques

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Figure: Transmission and busy medium probabilities for different packet lengths and number of nodes

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Average Energy Consumption

• In a randomly chosen slot time

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Average Energy Consumption

- In a randomly chosen slot time
 - $\bullet\,$ with probability $\tau\,$ the station transmits a packet

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Average Energy Consumption

- In a randomly chosen slot time
 - $\bullet\,$ with probability τ the station transmits a packet
 - with probability (1τ) the station is in a backoff stage with an average energy consumption E[B]

$$E = \tau \cdot P_{tx} \cdot t_{tx} + (1 - \tau) \cdot E[B]$$

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$$E[B] = E[IB] + \sum_{i=1}^{\infty} p_b^{(i-1)} \times (1 - p_b) \times [(i-1) \times E[CB] + i \times \mathcal{E}(CCA)];$$

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$$= E[IB] + \frac{1}{1 - p_b} \times \mathcal{E}(CCA) + \frac{pb}{1 - pb} \times E[CB];$$

$$(D \to (B) \to (B)$$

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Figure: Gain

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• Methodology for mapping the *free states* of a software protocol expressed as a TA to a physical device whose behavior is also expressed as an automaton with states of fixed or unbounded (but with lower limit constraint) duration

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 - Evaluate the performance of the optimized B-MAC radio driver for the platform WSN430 under the simulation environment Worldsens as well as on a realistic experimental platform
 - Long-term goal is to generate optimized device driver code.